

45. SU(3) Isoscalar Factors and Representation Matrices

Written by R.L. Kelly (LBNL).

The most commonly used SU(3) isoscalar factors, corresponding to the singlet, octet, and decuplet content of $8 \otimes 8$ and $10 \otimes 8$, are shown at the right. The notation uses particle names to identify the coefficients, so that the pattern of relative couplings may be seen at a glance. We illustrate the use of the coefficients below. See J.J de Swart, Rev. Mod. Phys. **35**, 916 (1963) for detailed explanations and phase conventions.

A $\sqrt{}$ is to be understood over every integer in the matrices; the exponent 1/2 on each matrix is a reminder of this. For example, the $\Xi \rightarrow \Omega K$ element of the $10 \rightarrow 10 \otimes 8$ matrix is $-\sqrt{6}/\sqrt{24} = -1/2$.

Intramultiplet relative decay strengths may be read directly from the matrices. For example, in decuplet \rightarrow octet + octet decays, the ratio of $\Omega^* \rightarrow \Xi \bar{K}$ and $\Delta \rightarrow N\pi$ partial widths is, from the $10 \rightarrow 8 \times 8$ matrix,

$$\frac{\Gamma(\Omega^* \rightarrow \Xi \bar{K})}{\Gamma(\Delta \rightarrow N\pi)} = \frac{12}{6} \times (\text{phase space factors}) . \quad (45.1)$$

Including isospin Clebsch-Gordan coefficients, we obtain, *e.g.*,

$$\frac{\Gamma(\Omega^{*-} \rightarrow \Xi^0 K^-)}{\Gamma(\Delta^+ \rightarrow p \pi^0)} = \frac{1/2}{2/3} \times \frac{12}{6} \times p.s.f. = \frac{3}{2} \times p.s.f. \quad (45.2)$$

Partial widths for $8 \rightarrow 8 \otimes 8$ involve a linear superposition of 8_1 (symmetric) and 8_2 (antisymmetric) couplings. For example,

$$\Gamma(\Xi^* \rightarrow \Xi \pi) \sim \left(-\sqrt{\frac{9}{20}} g_1 + \sqrt{\frac{3}{12}} g_2 \right)^2 . \quad (45.3)$$

The relations between g_1 and g_2 (with de Swart's normalization) and the standard D and F couplings that appear in the interaction Lagrangian,

$$\mathcal{L} = -\sqrt{2} D \text{Tr}(\{\bar{B}, B\}M) + \sqrt{2} F \text{Tr}([\bar{B}, B]M) , \quad (45.4)$$

where $[\bar{B}, B] \equiv \bar{B}B - B\bar{B}$ and $\{\bar{B}, B\} \equiv \bar{B}B + B\bar{B}$, are

$$D = \frac{\sqrt{30}}{40} g_1 , \quad F = \frac{\sqrt{6}}{24} g_2 . \quad (45.5)$$

Thus, for example,

$$\Gamma(\Xi^* \rightarrow \Xi \pi) \sim (F - D)^2 \sim (1 - 2\alpha)^2 , \quad (45.6)$$

where $\alpha \equiv F/(D + F)$. (This definition of α is de Swart's. The alternative $D/(D + F)$, due to Gell-Mann, is also used.)

The generators of SU(3) transformations, λ_a ($a = 1, 8$), are 3×3 matrices that obey the following commutation and anticommutation relationships:

$$[\lambda_a, \lambda_b] \equiv \lambda_a \lambda_b - \lambda_b \lambda_a = 2if_{abc}\lambda_c \quad (45.7)$$

$$\{\lambda_a, \lambda_b\} \equiv \lambda_a \lambda_b + \lambda_b \lambda_a = \frac{4}{3}\delta_{ab}I + 2d_{abc}\lambda_c , \quad (45.8)$$

where I is the 3×3 identity matrix, and δ_{ab} is the Kronecker delta symbol. The f_{abc} are odd under the permutation of any pair of indices, while the d_{abc} are even. The nonzero values are

2 45. $SU(3)$ isoscalar factors and representation matrices

$1 \rightarrow 8 \otimes 8$

$(\Lambda) \rightarrow (N\bar{K} \ \Sigma\pi \ \Lambda\eta \ \Xi K) = \frac{1}{\sqrt{8}} \begin{pmatrix} 2 & 3 & -1 & -2 \end{pmatrix}^{1/2}$

$8_1 \rightarrow 8 \otimes 8$

$\begin{pmatrix} N \\ \Sigma \\ \Lambda \\ \Xi \end{pmatrix} \rightarrow \begin{pmatrix} N\pi & N\eta & \Sigma K & \Lambda K \\ N\bar{K} & \Sigma\pi & \Lambda\pi & \Sigma\eta & \Xi K \\ N\bar{K} & \Sigma\pi & \Lambda\eta & \Xi K \\ \Sigma\bar{K} & \Lambda\bar{K} & \Xi\pi & \Xi\eta \end{pmatrix} = \frac{1}{\sqrt{20}} \begin{pmatrix} 9 & -1 & -9 & -1 \\ -6 & 0 & 4 & 4 & -6 \\ 2 & -12 & -4 & -2 \\ 9 & -1 & -9 & -1 \end{pmatrix}^{1/2}$

$8_2 \rightarrow 8 \otimes 8$

$\begin{pmatrix} N \\ \Sigma \\ \Lambda \\ \Xi \end{pmatrix} \rightarrow \begin{pmatrix} N\pi & N\eta & \Sigma K & \Lambda K \\ N\bar{K} & \Sigma\pi & \Lambda\pi & \Sigma\eta & \Xi K \\ N\bar{K} & \Sigma\pi & \Lambda\eta & \Xi K \\ \Sigma\bar{K} & \Lambda\bar{K} & \Xi\pi & \Xi\eta \end{pmatrix} = \frac{1}{\sqrt{12}} \begin{pmatrix} 3 & 3 & 3 & -3 \\ 2 & 8 & 0 & 0 & -2 \\ 6 & 0 & 0 & 6 \\ 3 & 3 & 3 & -3 \end{pmatrix}^{1/2}$

$10 \rightarrow 8 \otimes 8$

$\begin{pmatrix} \Delta \\ \Sigma \\ \Xi \\ \Omega \end{pmatrix} \rightarrow \begin{pmatrix} N\pi & \Sigma K \\ N\bar{K} & \Sigma\pi & \Lambda\pi & \Sigma\eta & \Xi K \\ \Sigma\bar{K} & \Lambda\bar{K} & \Xi\pi & \Xi\eta \\ \Xi\bar{K} \end{pmatrix} = \frac{1}{\sqrt{12}} \begin{pmatrix} -6 & 6 \\ -2 & 2 & -3 & 3 & 2 \\ 3 & -3 & 3 & 3 \\ 12 \end{pmatrix}^{1/2}$

$8 \rightarrow 10 \otimes 8$

$\begin{pmatrix} N \\ \Sigma \\ \Lambda \\ \Xi \end{pmatrix} \rightarrow \begin{pmatrix} \Delta\pi & \Sigma K \\ \Delta\bar{K} & \Sigma\pi & \Sigma\eta & \Xi K \\ \Sigma\pi & \Xi K \\ \Sigma\bar{K} & \Xi\pi & \Xi\eta & \Omega K \end{pmatrix} = \frac{1}{\sqrt{15}} \begin{pmatrix} -12 & 3 \\ 8 & -2 & -3 & 2 \\ -9 & 6 \\ 3 & -3 & -3 & 6 \end{pmatrix}^{1/2}$

$10 \rightarrow 10 \otimes 8$

$\begin{pmatrix} \Delta \\ \Sigma \\ \Xi \\ \Omega \end{pmatrix} \rightarrow \begin{pmatrix} \Delta\pi & \Delta\eta & \Sigma K \\ \Delta\bar{K} & \Sigma\pi & \Sigma\eta & \Xi K \\ \Sigma\bar{K} & \Xi\pi & \Xi\eta & \Omega K \\ \Xi\bar{K} & \Omega\eta \end{pmatrix} = \frac{1}{\sqrt{24}} \begin{pmatrix} 15 & 3 & -6 \\ 8 & 8 & 0 & -8 \\ 12 & 3 & -3 & -6 \\ 12 & -12 \end{pmatrix}^{1/2}$

abc	f_{abc}	abc	d_{abc}	abc	d_{abc}
123	1	118	$1/\sqrt{3}$	355	$1/2$
147	$1/2$	146	$1/2$	366	$-1/2$
156	$-1/2$	157	$1/2$	377	$-1/2$
246	$1/2$	228	$1/\sqrt{3}$	448	$-1/(2\sqrt{3})$
257	$1/2$	247	$-1/2$	558	$-1/(2\sqrt{3})$
345	$1/2$	256	$1/2$	668	$-1/(2\sqrt{3})$
367	$-1/2$	338	$1/\sqrt{3}$	778	$-1/(2\sqrt{3})$
458	$\sqrt{3}/2$	344	$1/2$	888	$-1/\sqrt{3}$
678	$\sqrt{3}/2$				

The λ_a 's are

$$\lambda_1 = \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda_2 = \begin{pmatrix} 0 & -i & 0 \\ i & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \quad \lambda_3 = \begin{pmatrix} 1 & 0 & 0 \\ 0 & -1 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

$$\lambda_4 = \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix} \quad \lambda_5 = \begin{pmatrix} 0 & 0 & -i \\ 0 & 0 & 0 \\ i & 0 & 0 \end{pmatrix} \quad \lambda_6 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$\lambda_7 = \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & -i \\ 0 & i & 0 \end{pmatrix} \quad \lambda_8 = \frac{1}{\sqrt{3}} \begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & -2 \end{pmatrix}$$

Equation (45.7) defines the Lie algebra of SU(3). A general d -dimensional representation is given by a set of $d \times d$ matrices satisfying Eq. (45.7) with the f_{abc} given above. Equation (45.8) is specific to the defining 3-dimensional representation.